



# Triple Solutions to Boundary Value Problems on Time Scales

R. P. AGARWAL

Department of Mathematics  
National University of Singapore  
10 Kent Ridge Crescent, Singapore 119260

D. O'REGAN

Department of Mathematics  
National University of Ireland  
Galway, Ireland

(Received August 1999; accepted September 1999)

**Abstract**—Criteria are developed for the existence of three nonnegative solutions to nonlinear differential equations on time scales. © 2000 Elsevier Science Ltd. All rights reserved.

**Keywords**—Multiple solutions, Differential equations on time scales, Leggett Williams Fixed-Point Theorem.

## 1. INTRODUCTION

In this paper, we present results which guarantee the existence of three solutions to nonlinear equations on measure chains of the form

$$\begin{aligned} y^\Delta(t) + f(y(\sigma(t))) &= 0, & \text{for } t \in [a, b]. \\ \alpha y(a) - \beta y^\Delta(a) &= 0, & \alpha > 0, \quad \beta \geq 0, \\ y^\Delta(\sigma(b)) &= 0. \end{aligned} \tag{1.1}$$

To understand (1.1), we need to recall some standard definitions (see [1–8] for an introduction to this subject).

**DEFINITION 1.1.** Let  $\mathbf{T}$  be a closed subset of  $\mathbf{R}$  with the property that

$$\sigma(t) = \inf \{ \tau > t : \tau \in \mathbf{T} \} \in \mathbf{T} \quad \text{and} \quad \rho(t) = \sup \{ \tau < t : \tau \in \mathbf{T} \} \in \mathbf{T},$$

for all  $t \in \mathbf{T}$ . We assume throughout that  $\mathbf{T}$  has the topology that it inherits from the standard topology on  $\mathbf{R}$ .

Throughout this paper,  $a < b$  are points in  $\mathbf{T}$ . Let

$$[a, b] = \{ t \in \mathbf{T} : a \leq t \leq b \}.$$

DEFINITION 1.2. Fix  $t \in \mathbf{T}$ . Let  $y : \mathbf{T} \rightarrow \mathbf{R}$ . Then we define  $y^\Delta(t)$  to be the number (if it exists) with the property that given  $\epsilon > 0$ , there is a neighborhood  $U$  of  $t$  with

$$|[y(\sigma(t)) - y(s)] - y^\Delta(t) [\sigma(t) - s]| < \epsilon |\sigma(t) - s|,$$

for all  $s \in U$ . We call  $y^\Delta(t)$  the derivative of  $y(t)$ .

DEFINITION 1.3. If  $F^\Delta(t) = f(t)$ , then we define the integral by

$$\int_a^t f(\tau) \Delta \tau = F(t) - F(a).$$

To show the existence of three nonnegative solutions to (1.1), we will use the Leggett Williams Fixed-Point Theorem [9,10]. Recently, [9–13] this fixed-point theorem has been used to establish results for differential and difference equations. In this paper, we provide a new existence result for differential equations on time scales. In fact, our result is new when  $\mathbf{T} = \mathbf{R}$  (the differential equation case) and when  $\mathbf{T} = \mathbf{Z}$  (the discrete case).

For the remainder of this section, we gather together some results from the literature that will be needed in Section 2. The Green's function for the boundary value problem

$$\begin{aligned} -y^{\Delta\Delta}(t) &= 0, & \text{for } t \in [a, b], \\ \alpha y(a) - \beta y^\Delta(a) &= 0, & \alpha > 0, \quad \beta \geq 0, \\ y^\Delta(\sigma(b)) &= 0 \end{aligned} \tag{1.2}$$

is given by [5,6],

$$G(t, s) = \begin{cases} \frac{\alpha(t-a) + \beta}{\alpha}, & t \leq s, \\ \frac{\alpha(\sigma(s)-a) + \beta}{\alpha}, & \sigma(s) \leq t. \end{cases}$$

It is easy to check since

$$\frac{G(t, s)}{G(\sigma(s), s)} = \begin{cases} \frac{\alpha(t-a) + \beta}{\alpha(\sigma(s)-a) + \beta}, & t \leq s, \\ 1, & \sigma(s) \leq t, \end{cases}$$

that

$$0 \leq G(t, s) \leq G(\sigma(s), s), \quad \text{for } t \in [a, \sigma^2(b)] \quad \text{and} \quad s \in [a, \sigma(b)] \tag{1.3}$$

and

$$G(t, s) \geq k G(\sigma(s), s), \quad \text{for } t \in \left[ \frac{\sigma(b) + 3a}{4}, \sigma^2(b) \right] \quad \text{and} \quad s \in [a, \sigma(b)]; \tag{1.4}$$

here

$$k = \frac{\alpha(\sigma(b) - a) + 4\beta}{4\alpha(\sigma^2(b) - a) + 4\beta}. \tag{1.5}$$

REMARK 1.1. We could replace  $(\sigma(b) + 3a)/4$  in (1.4) by any  $\mu \in \mathbf{R}$  with  $a < \mu < \sigma^2(b)$  provided  $k$  in (1.5) is adjusted to  $(\alpha(\mu - a) + \beta)/(\alpha(\sigma^2(b) - a) + \beta)$ .

$E = (E, \|\cdot\|)$  is a Banach space and  $C \subset E$  a cone. By a concave nonnegative continuous functional  $\psi$  on  $C$ , we mean a continuous mapping  $\psi : C \rightarrow [0, \infty)$  with

$$\psi(\lambda x + (1 - \lambda)y) \geq \lambda \psi(x) + (1 - \lambda)\psi(y), \quad \text{for all } x, y \in C \quad \text{and all } \lambda \in [0, 1].$$

Let  $K, L, r > 0$  be constants with  $C$  and  $\psi$  as defined above. Let

$$C_K = \{y \in C : \|y\| < K\} \quad \text{and} \quad C(\psi, r, L) = \{y \in C : \psi(y) \geq r \text{ and } \|y\| \leq L\}.$$

We now state the Leggett Williams Fixed-Point Theorem [9,10].

**THEOREM 1.1.** *Let  $E = (E, \|\cdot\|)$  be a Banach space,  $C \subset E$  a cone of  $E$  and  $R > 0$  a constant. Suppose there exists a concave nonnegative continuous functional  $\psi$  on  $C$  with  $\psi(y) \leq \|y\|$  for  $y \in \overline{C_R}$  and let  $A : \overline{C_R} \rightarrow \overline{C_R}$  be a continuous, compact map. Assume there are numbers  $r, L$ , and  $K$  with  $0 < r < L < K \leq R$  such that*

- (H1)  $\{y \in C(\psi, L, K) : \psi(y) > L\} \neq \emptyset$  and  $\psi(Ay) > L$  for all  $y \in C(\psi, L, K)$ ;
- (H2)  $\|Ay\| < r$  for all  $y \in \overline{C_r}$ ;
- (H3)  $\psi(Ay) > L$  for all  $y \in C(\psi, L, R)$  with  $\|Ay\| > K$ .

*Then  $A$  has at least three fixed points  $y_1, y_2$ , and  $y_3$  in  $\overline{C_R}$ . Furthermore, we have*

$$y_1 \in C_r, \quad y_2 \in \{y \in C(\psi, L, R) : \psi(y) > L\} \quad \text{and} \quad y_3 \in \overline{C_R} \setminus (C(\psi, L, R) \cup \overline{C_r}).$$

## 2. EXISTENCE

We use Theorem 1.1 to establish the existence of three nonnegative solutions to (1.1). By  $C[a, \sigma^2(b)]$ , we mean the Banach space of continuous functions  $y : [a, \sigma^2(b)] \rightarrow \mathbf{R}$  equipped with the norm  $\|y\|_0 = \sup_{t \in [a, \sigma^2(b)]} |y(t)|$ .

The following conditions will be assumed:

$$f : [0, \infty) \rightarrow [0, \infty) \text{ is continuous and nondecreasing} \quad (2.1)$$

$$\exists r > 0 \text{ with } f(r) \sup_{t \in [a, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) \Delta s < r \quad (2.2)$$

$$[a, \sigma^2(b)] \text{ is such that } \eta = \min \left\{ \tau \in \mathbf{T} : \tau \geq \frac{\sigma(b) + 3a}{4} \right\} \quad (2.3)$$

$$\text{exists and satisfies } \frac{\sigma(b) + 3a}{4} \leq \eta < \sigma(b)$$

$$\exists L > r \text{ with } f(L) \min_{t \in [\eta, \sigma^2(b)]} \int_\eta^{\sigma(b)} G(t, s) \Delta s > L \quad (2.4)$$

and

$$\exists R \geq Lk^{-1} \text{ with } f(R) \sup_{t \in [a, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) \Delta s \leq R; \quad (2.5)$$

here  $k$  is as in (1.5).

**THEOREM 2.1.** *Suppose (2.1)–(2.5) hold. Then (1.1) has three nonnegative solution  $y_1, y_2$ , and  $y_3$  in  $C[a, \sigma^2(b)]$  with  $y_i^{\Delta \Delta} \in C_{rd}[a, b]$  (note  $y_i^\sigma = y_i \circ \sigma$  is  $rd$ -continuous on  $[a, b]$ ) for  $i = 1, 2, 3$  and*

$$|y_1|_0 < r, \quad y_2(t) > L, \quad \text{for } t \in [\eta, \sigma^2(b)] \text{ and } |y_3|_0 > r \text{ with } \min_{t \in [\eta, \sigma^2(b)]} y_3(t) < L.$$

**REMARK 2.1.** Note  $C_{rd}[a, b]$  is the space of  $rd$ -continuous functions [1, 8] on  $[a, b]$ .

**REMARK 2.2.** Notice  $(\sigma(b) + 3a)/4$  could be replaced by any  $\bar{\mu} \in \mathbf{R}$ ,  $a < \bar{\mu} < \sigma(b)$  (see Remark 1.1) provided  $k$  in (1.5) is adjusted to  $(\alpha(\bar{\mu} - a) + \beta)/(\alpha(\sigma^2(b) - a) + \beta)$ .

**PROOF.** Let

$$E = (C[a, \sigma^2(b)], \|\cdot\|_0) \quad \text{and} \quad C = \{y \in C[a, \sigma^2(b)] : y(t) \geq 0, \text{ for } t \in [a, \sigma^2(b)]\}.$$

Now let  $A : C \rightarrow C$  be defined by

$$Ay(t) = \int_a^{\sigma(b)} G(t, s) f(y(\sigma(s))) \Delta s, \quad \text{for } t \in [a, \sigma^2(b)]; \quad (2.6)$$

here  $y \in C$ . It is immediate from the ideas in [3] that

$A : C \rightarrow C$  is continuous and completely continuous.

For  $y \in C$ , let

$$\psi(y) = \min_{t \in [\eta, \sigma^2(b)]} y(t).$$

Next choose and fix  $K$  so that

$$L k^{-1} \leq K \leq R; \quad (2.7)$$

this is possible since  $R \geq L k^{-1}$ . Let

$$C_r = \{y \in C : |y|_0 < r\}, \quad C_R = \{y \in C : |y|_0 < R\}$$

and

$$C(\psi, L, K) = \{y \in C : \psi(y) \geq L \text{ and } |y|_0 \leq K\}, \quad C(\psi, L, R) = \{y \in C : \psi(y) \geq L \text{ and } |y|_0 \leq R\}.$$

We first show condition (H2) of Theorem 1.1 holds. If  $y \in \overline{C_r}$ , then (2.6) and [8, Theorem 1.4.3 (iii)] guarantee that

$$\begin{aligned} A y(t) &= \int_a^{\sigma(b)} G(t, s) f(y(\sigma(s))) \Delta s \leq f(|y|_0) \int_a^{\sigma(b)} G(t, s) \Delta s \\ &\leq f(r) \sup_{t \in [a, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) \Delta s, \end{aligned}$$

for  $t \in [a, \sigma^2(b)]$ . This together with (2.2) yields

$$|A y|_0 \leq f(r) \sup_{t \in [a, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) \Delta s < r.$$

Thus, condition (H2) of Theorem 1.1 holds. Similarly, we have  $A : \overline{C_R} \rightarrow \overline{C_R}$ .

Next, we show condition (H1) of Theorem 1.1 holds. First, notice if

$$u(t) = \frac{L + K}{2}, \quad \text{for } t \in [a, \sigma^2(b)],$$

then  $u \in \{y \in C(\psi, L, K) : \psi(y) > L\}$ . Also if  $y \in C(\psi, L, K)$ , then  $\psi(y) = \min_{t \in [\eta, \sigma^2(b)]} y(t) \geq L$  and  $|y|_0 \leq K$ , so  $y(s) \in [L, K]$  for  $s \in [\eta, \sigma^2(b)]$  and as a result

$$y(\sigma(x)) \in [L, K], \quad \text{for } x \in [\eta, \sigma(b)]. \quad (2.8)$$

This together with (2.4) and [8 (Theorem 1.4.3 (iii))] yields

$$\begin{aligned} \psi(A y) &= \min_{t \in [\eta, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) f(y(\sigma(s))) \Delta s \geq \min_{t \in [\eta, \sigma^2(b)]} \int_{\eta}^{\sigma(b)} G(t, s) f(y(\sigma(s))) \Delta s \\ &\geq f(L) \min_{t \in [\eta, \sigma^2(b)]} \int_{\eta}^{\sigma(b)} G(t, s) \Delta s > L, \end{aligned}$$

so condition (H1) of Theorem 1.1 is satisfied. Finally, to see that (H3) of Theorem 1.1 holds, let  $y \in C(\psi, L, R)$  with  $|A y|_0 > K$ . First, notice (1.3) and [8, Theorem 1.4.3 (iii)] imply

$$|A y|_0 \leq \int_a^{\sigma(b)} G(\sigma(s), s) f(y(\sigma(s))) \Delta s$$

and this together with (1.4), [8, Theorem 1.4.3 (iii)], and (2.7) yields

$$\begin{aligned} \psi(A y) &= \min_{t \in [\eta, \sigma^2(b)]} \int_a^{\sigma(b)} G(t, s) f(y(\sigma(s))) \Delta s \\ &\geq \int_a^{\sigma(b)} k G(\sigma(s), s) f(y(\sigma(s))) \Delta s \\ &\geq k |A y|_0 > k K \geq L. \end{aligned}$$

Thus, condition (H3) of Theorem 1.1 holds. Now apply Theorem 1.1. ■

## REFERENCES

1. R.P. Agarwal and M. Bohner, Basic calculus on time scales and some of its applications, *Results in Mathematics* **35**, 3–22, (1999).
2. R.P. Agarwal, M. Bohner and P. Wong, Sturm–Liouville eigenvalue problems on time scales, *Applied Mathematics and Computation* **99**, 153–166, (1999).
3. R.P. Agarwal and D. O'Regan, Nonlinear boundary value problems on time scales, *Nonlinear Analysis* (to appear).
4. B. Aulbach and S. Hilgar, Linear dynamic processes with inhomogeneous time scale, In *Nonlinear Dynamics and Quantum Dynamical Systems*, Akademie Verlag, Berlin, (1990).
5. L.H. Erbe and A. Peterson, Green's functions and comparison theorems for differential equations on measure chains, *Dynamics of Continuous, Discrete and Impulsive Systems* **6**, 121–138, (1999).
6. L.H. Erbe and A. Peterson, Positive solutions for a nonlinear differential equation on a measure chain, *Mathl. Comput. Modelling* (to appear).
7. S. Hilgar, Analysis on measure chains—A unified approach to continuous and discrete calculus, *Results in Mathematics* **18**, 18–56, (1990).
8. B. Kaymakçalan, V. Lakshmikantham and S. Sivasundaram, *Dynamical Systems on Measure Chains*, Kluwer Acad., Dordrecht, (1996).
9. D. Guo and V. Lakshmikantham, *Nonlinear Problems in Abstract Cones*, Academic Press, San Diego, CA, (1988).
10. R.W. Leggett and L.R. Williams, Multiple positive fixed points of nonlinear operators on ordered Banach spaces, *Indiana Math. J.* **28**, 673–688, (1979).
11. R.P. Agarwal, D. O'Regan and P.J.Y. Wong, *Positive Solutions of Differential, Difference and Integral Equations*, Kluwer Acad., Dordrecht, (1999).
12. D. Anderson, R.I. Avery and A.C. Peterson, Three positive solutions to a discrete focal boundary value problem, *J. Comput. Appl. Math.* **88**, 103–118, (1998).
13. P.J. Wong and R.P. Agarwal, Criteria for multiple solutions of difference and partial difference equations subject to multipoint conjugate conditions, *Nonlinear Analysis* (to appear).